

$$\Delta U = \Delta Q + \Delta W$$

$$E = E_{pot} + E_{kin} + U$$

$$S = S_{term} + S_{konf}$$

$$\Delta_e S_m \simeq -R(x_A \ln x_A + x_B \ln x_B)$$

$$R = \epsilon \sigma (T_1^4 - T_2^4)$$

$$\frac{d\rho_E}{dt} = \frac{1}{V} \frac{dE}{dt} = \frac{1}{(\Delta x)^3} \cdot \frac{dE}{dt}$$

$$c_f(x,t) = \frac{c_0}{2} \left[ 1 - \operatorname{erf} \left( \frac{x}{\sqrt{4Dt}} \right) \right]$$

$$D = \frac{k_B T}{6\pi\eta R}$$

$$Pe = \frac{t_{diff}}{t_{konv}} = \frac{L \cdot v}{D}$$

$$I_V = \frac{\pi \cdot R_o^4}{8\eta} \cdot \frac{\Delta P}{L}$$

$$M_n = \frac{\sum n_i M_i}{\sum n_i}$$

$$f_s = T \left( \frac{\partial f}{\partial T} \right)_{\lambda, V}$$

$$p = \frac{I_{wv} - I_{vh}}{I_{wv} + I_{vh}}$$

$$|\vec{L}| = L = \frac{h}{2\pi} \sqrt{l(l+1)} \approx \frac{h}{2\pi} l$$

$$|\vec{\mu}_l| = \frac{e}{2m} |\vec{L}| = \left( \frac{eh}{4\pi m_e} \right) l$$

$$|\vec{\mu}_s| = \frac{eh}{4\pi m_e} = \mu_B$$

$$\Delta E = 2\mu_B = hf$$

$$\frac{N_2}{N_1} = e^{-\frac{\Delta E}{kT}}$$

$$E_{Cb} = \frac{q_1 * q_2}{\epsilon * r}$$

$$\Delta W_{mech} = \Delta U - \Delta Q - \sum_i \Delta W_i$$

$$\Delta S_m(T_{op}) = \frac{\Delta H_m}{T_{op}} > 0$$

$$\frac{dE}{dt} = I_{be} + I_{ki} = I$$

$$\frac{\partial c}{\partial t} = D \nabla^2 c$$

$$\frac{\partial \rho_E}{\partial t} = -\nabla \cdot \mathbf{j}_E = -\operatorname{div} \mathbf{j}_E$$

$$c_f(x,t) = c_0 \left[ 1 - \operatorname{erf} \left( \frac{x}{\sqrt{4Dt}} \right) \right]$$

$$\ln \left( \frac{2c_i - c_0}{c_0} \right) = -\frac{2A P_{erm}}{V} \cdot t$$

$$\pi_{id} = \frac{RT}{M_2} c_2$$

$$v_x = \frac{I_V}{R_o^2 \pi} = \frac{R_o^2}{8\eta} \cdot \frac{\Delta P}{L} = \frac{1}{2} v_{max}$$

$$D = \frac{k_B T}{6\pi\eta a_r}$$

$$E = E_{max} \cdot \sin \left( 2\pi \frac{t}{T} + 2\pi \frac{x}{\lambda} + \Phi \right)$$

$$M_n = \frac{\sum n_i M_i}{\sum n_i}$$

$$f_s = T \left( \frac{\partial f}{\partial T} \right)_{\lambda, V}$$

$$2d \sin \theta = n \lambda$$

$$d \approx \lambda$$

$$\varepsilon = \frac{C}{C_0} = \frac{E_0}{E} > 1$$

$$\delta_{lat} \sim \frac{F}{2R} \cdot \lambda$$

$$\Delta p(t, x) = \Delta p_{max} \sin \left[ 2\pi \left( \frac{t}{T} - \frac{x}{\lambda} \right) \right]$$

$$c \cdot T = \lambda, \quad c = f \cdot \lambda$$

$$\Delta G_i^{\text{ref}}(z') = (1 - f(z')) * (\Delta G_i^{\text{ref, chex}} - \Delta G_i^{\text{ref, water}})$$

$$\kappa = \frac{4\pi}{3} \frac{E r^4}{L^3}$$

$$\kappa = \frac{F}{\Delta L}$$

$$\varepsilon = \frac{\Delta L}{L}$$

$$\sigma = \frac{F}{A}$$

$$\frac{F}{A} = E \frac{\Delta L}{L}$$

$$\delta = 0,61 \cdot \lambda / (n \cdot \sin \omega)$$

$$\Delta Q = Q_{metabolizmus} + Q_{vesztesség}$$

$$j_Q = -k \nabla T$$

$$BMR = \frac{dQ}{dt} \Big|_{nyugalom}$$

$$S = k_B \ln W$$

$$\Delta U = T \Delta S - p \Delta V + \sum_{i=1}^K \mu_i \Delta n_i + \dots +$$

$$P_{erm} \propto K_m \cdot D$$

$$S(T) = \int_0^T \frac{C_p}{T} dT + \Delta S_{konfig}$$

$$\Delta S = \int \frac{C_m}{T} dT$$

$$W = \frac{(N_A + N_B)!}{N_A! \cdot N_B!}$$

$$\Delta S = \frac{Q_{forr}}{T_{fp}} = \frac{\Delta H_{forr}}{T_{fp}}$$

$$\frac{\partial T}{\partial t} = \alpha \nabla^2 T$$

$$j_n = -D \nabla c$$

$$j_Q = -k \nabla T$$

$$j_i = -\eta \nabla v$$

$$\left( \frac{\partial Q}{\partial T} \right)_V < \left( \frac{\partial Q}{\partial T} \right)_p$$

$$dS_{term} = \frac{C_V}{T} dT < 0$$

$$\alpha = \frac{k}{\rho \cdot C_p}$$

$$-\frac{dQ}{dt} = \rho c_p (T_{ki} - T_{be}) \frac{dV}{dt}$$

$$-\frac{dQ}{dt} = \Delta h \cdot (\rho_{lev}^{ki} - \rho_{lev}^{be}) \frac{dV}{dt}$$

$$\frac{dQ}{dt} = f \cdot BMR$$

$$\frac{f}{A} = E \frac{\Delta l}{l_o}$$

$$\frac{\partial c_A}{\partial t} = D \cdot \operatorname{div} \cdot (\operatorname{grad} \cdot c_A) = D \nabla^2 c_A$$

$$\frac{d\gamma}{dt} = \frac{d}{dt} \left( \frac{du_x}{dy} \right) = \frac{d}{dy} \left( \frac{du_x}{dt} \right) = \frac{dv_x}{dy}$$

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$$\eta(T) = \eta_o \cdot \exp \left( \frac{E_a}{RT} \right)$$

$$[\eta] = \lim_{c \rightarrow 0} \eta_{red}$$

$$\eta_{red} = \frac{\eta_{sp}}{c}$$

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$$f_\eta = 6\pi\eta a_r v_x$$

$$\Phi_{em} = \frac{N_{em}}{N_{absz}} = \frac{k_{em}}{k_{em} + k_{belsz} + k_{kulsz}} \approx \int F(v) dv$$

$$c^* = \frac{N_m \cdot V_m}{V_{coil}}$$

$$P_{re} = konst \cdot U^2 \cdot I \cdot Z$$

$$Konst = 1.1 \cdot 10^{-9} \cdot 1/V$$

$$q_e U = \frac{1}{2} m_e v^2 = hf_h = h \frac{c}{\lambda_h}$$

$$\lambda_h = \frac{h \cdot c}{q_e \cdot U}$$

$$\mu_Z = m_S \frac{h}{2\pi} = m_S \hbar$$

$$L \cos \Theta = L_z = \frac{h}{2\pi} m_l$$

$$m_S = \pm \frac{1}{2}$$

$$E = E_0 - \left| \vec{H} \right| * \left| \vec{\mu} \right| * \cos \phi$$

$$\Delta E \sim 2\mu_Z B$$

$$\Delta E = E_2 - E_1 = (E_o - E_{magn.2}) - (E_0 - E_{magn.1}) = \mu_Z B \cos \phi + \mu_Z B \cos \phi \approx 2\mu_Z B$$

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$$E_{prot} = W_{rot} E_{rot} + W_{atr} E_{atr} + W_{rep} E_{rep} + W_{solv} E_{solv} + W_{pair} E_{pair}$$

$$E_{solv} = - \sum_i \sum_{j>i}^{natom} \left\{ \frac{2\Delta G_i^{free}}{4\pi\sqrt{\pi}\lambda_i r_{ij}^2} \exp(-d_{ij}^2) V_j + \frac{2\Delta G_j^{free}}{4\pi\sqrt{\pi}\lambda_j r_{ij}^2} \exp(-d_{ji}^2) V_i \right\}$$