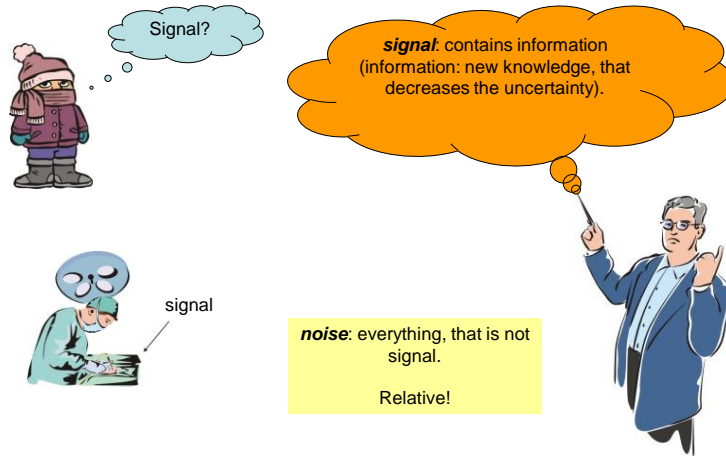


Medical signal processing



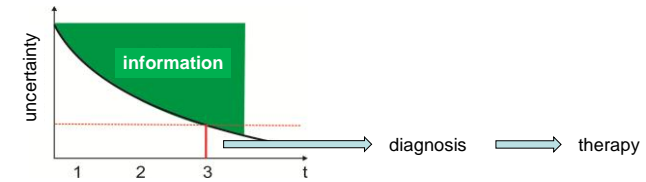
Information



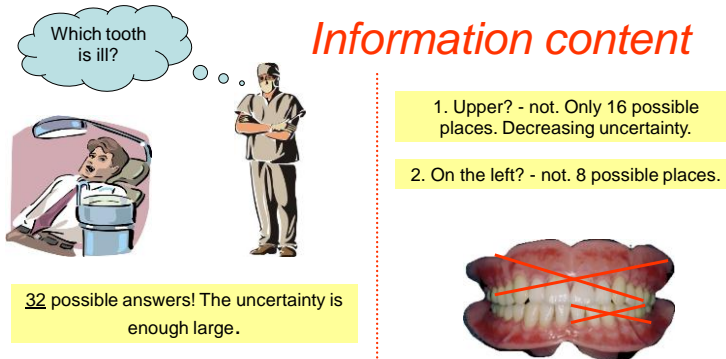
1. Enters.
2. Complaint?
3. Which?

information:

1. A patient.
2. I've a toothache.
3. Third molar.



Information content



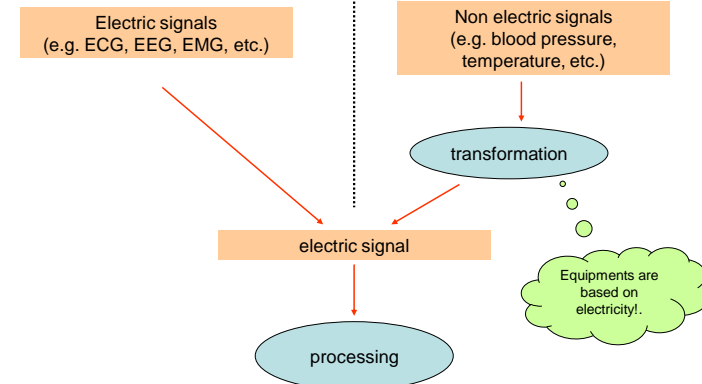
Five right questions are necessary to identify the place!

Information content: 5 bit ($2^5 = 32$)

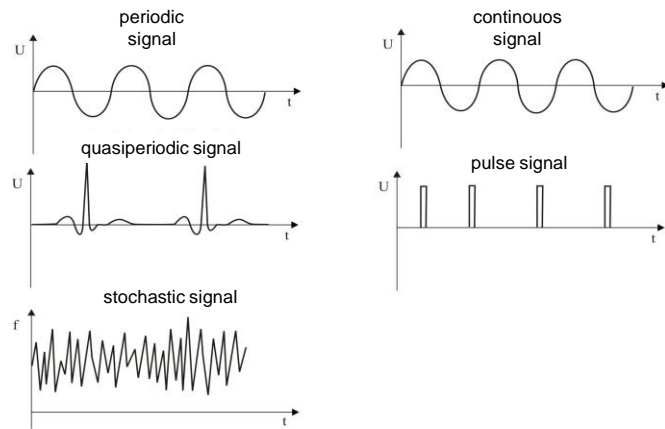
Bit: unit of the information.



Classification of the signals 1.



Classification of the signals 2.

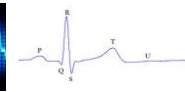


Classification of the signals 3.

analog signal



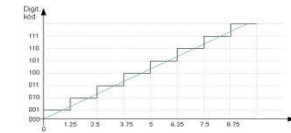
sound



ecg

In a certain range every value is possible.

digital signal



Only a finite no. of values are possible.



height:
analog signal

measurement



height:
175 cm
(only discrete values)

Signal and noise

Noise is random normally!

Ideal case: there is no noise!

Real measurements: noise is always present!

Signal to noise ratio:

The ratio of the quantity used to characterize the strength of the signal and the noise.

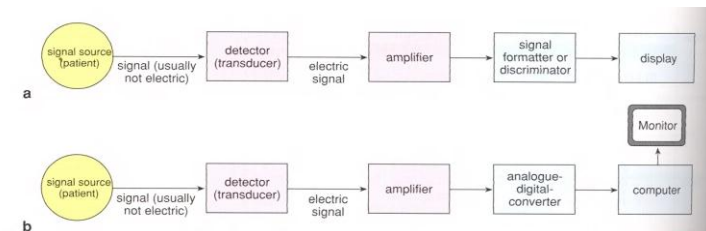
Higher value is better!

How can we increase?

increasing the signal

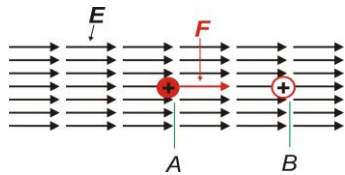
decreasing the noise

Signal processing



Electric field

Force arises on charges. (E – electric field strength)
Static (constant in time) field is produced by charges in rest.



$$\vec{F} = \vec{E} \cdot Q$$

Voltage (V):
unit: volt (V)

$$U_{AB} = \frac{W_{AB}}{Q}$$

Work:

$$W_{AB} = \sum \vec{F} \cdot \vec{\Delta s} = Q \cdot \sum \vec{E} \cdot \vec{\Delta s}$$



Electric potential

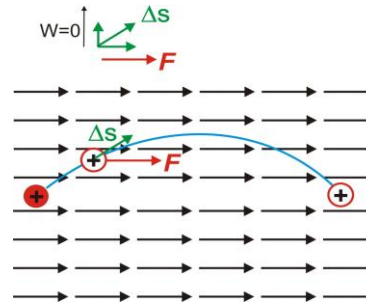
In static field the work is independent from the path.

Let B is in the infinity:

$$U_A = U_{A\infty}$$

U_A – the potential at A , and:

$$U_{AB} = U_A - U_B$$

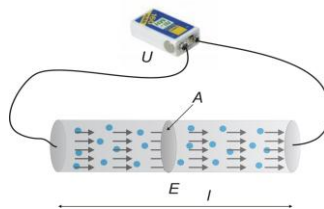


Electric current

Definition: Ordered, unidirectional motion of charges. Its strength is the I . Unit: amper (A)

$$I = \frac{\Delta Q}{\Delta t}$$

$$E = \frac{U}{l}$$

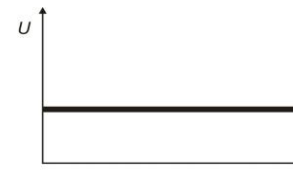


Depends on the material, A cross-section and E field strength.



Direct current (DC)

The direction of the current doesn't change.



Electric power (P):

According to the definition of the voltage: $W = QV$.

The current is: $Q = It$.

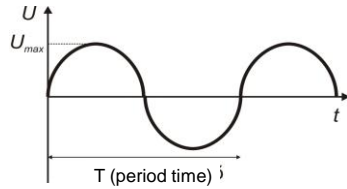
The result:

$$P_{electric} = \frac{W_{el}}{t} = U \cdot I$$



Alternating current (AC)

The direction of the current changes periodically.



frequency: No. of periods during unit time.

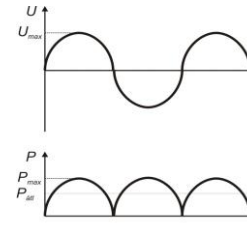
$$f = \frac{1}{T}$$

$$\omega = 2 \cdot \pi \cdot f$$

$$U = U_{\max} \cdot \sin(\omega t)$$

Effective voltage, effective current

Definition: These are the value of a direct current, that has the same power than the given alternating current.



$$P = U \cdot I = I^2 \cdot R = \frac{U^2}{R}$$

$$U_{\text{eff}} = \frac{U_{\text{max}}}{\sqrt{2}} \quad \text{or} \quad I_{\text{eff}} = \frac{I_{\text{max}}}{\sqrt{2}}$$

(The equations above are valid only for sinusoidal current.)



Conductors and insulators

conductors: contain movable charges.

Metals: electrons

Electrolytes: ions



insulators: contain immobile charges.

The best insulator is the vacuum.

Elements in a electric circuit

passive



resistor



capacitor



inductivity

active

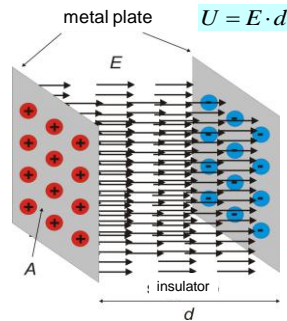


diode



transistor

Capacitor



There is a homogenous electric between plates if they are charged.

The strength of the electric field depends on the voltage (V) between plates and the charges (Q) on them.

$$C = \frac{Q}{U}$$

$$C = \epsilon \frac{A}{d}$$

C is the capacitance.
unit: farade (F)

Resistance

The average speed of the charges is determined by the E and the structure of the material.
The current depends on the no. of electrons passing through the cross-section during unit time that is influenced by the average speed.
This property of the conductor is called resistance (R).
unit: ohm (Ω)

Ohm's law:

$$R = \frac{U}{I}$$

The R depends on the material, the cross-section and on the length.
(ρ = resistivity.)

$$R = \rho \frac{l}{A}$$



Conductance

This is reciprok to the resistance. Unit is the siemens (S).

The conductivity (σ) is reciprok to the resistivity.

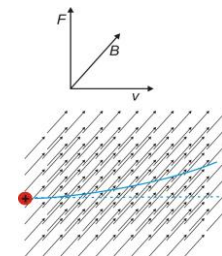
$$\sigma = \frac{1}{\rho}$$

Magnetic field

Force is exerted on moving charges only.
Its strength is characterized by the B (magnetic field vector).

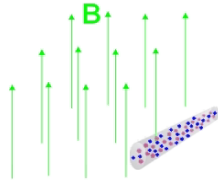
Lorentz force:

proportional to the Q,
the speed of the charge and the B.



Electromagnetic induction

Motion of a conductor in magnetic field.



The Lorentz force is exerted on the moveable electrons. The motion of the electrons produces charge separation in the material. This separation generates voltage.

Inductance



Permanent current produces a magnetic field in a coil. The resistance of the coil is zero in ideal case and so the voltage drop is also zero.

Alternating current produces periodically changing magnetic field. The consequence of this magnetic field is an induced voltage.

The produced voltage is proportional to the speed of the current changing in time. The proportionality factor is the inductivity (L).

Unit: H – henry.

The impedance (X) („resistance” in the case of the alternating current)

resistance:

$$X_R = R$$

doesn't depend on the frequency

capacitor:

$$X_C = \frac{1}{\omega C}$$

depends on the frequency

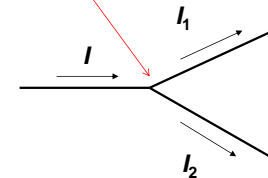
inductance:

$$X_L = \omega L$$

depends on the frequency

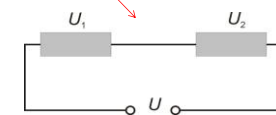
Kirchoff's laws

junction rule (current law)



$$I = I_1 + I_2$$

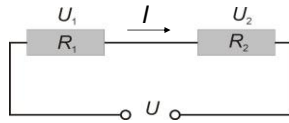
loop rule (voltage law)



$$U = - (U_1 + U_2)$$

Serial, parallel circuit

Serial circuit

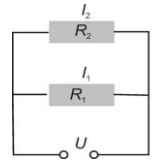


$$U = U_1 + U_2$$

$$IR = IR_1 + IR_2$$

$$R = R_1 + R_2$$

Parallel circuit



$$I = I_1 + I_2$$

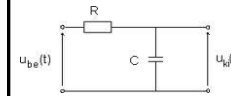
$$\frac{U}{R} = \frac{U}{R_1} + \frac{U}{R_2}$$

$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$$

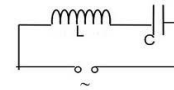
Electric circuits

A unit consists of elements.

simple
(consists of passive elements)



RC circuit



LC circuit

complex
(consists of passive and active elements)



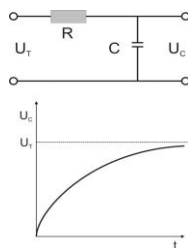
integrated circuit



amplifier

DC behavior of a RC-circuit

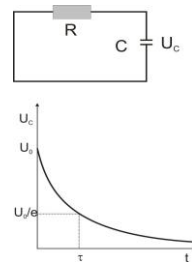
charging



$$U_C = U_T \cdot \left(1 - e^{-\frac{t}{RC}}\right)$$

$$\tau = RC$$

discharging

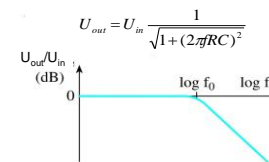
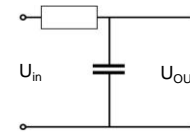


$$U_C = U_0 \cdot e^{-\frac{t}{RC}}$$

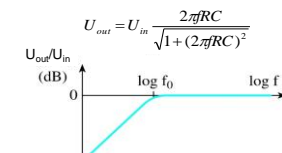
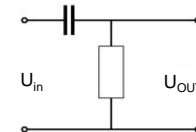
τ = time constant

AC behavior of a RC-circuit

Lowpass filter

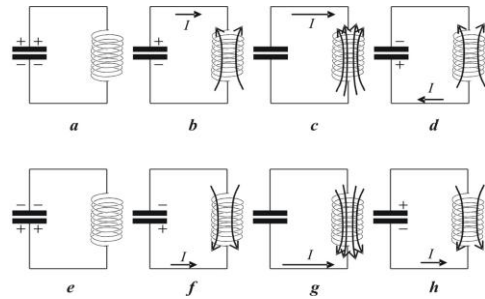


Highpass filter



Resonant circuit (LC-circuit)

Electric (in the capacitor) and
magnetic (in the coil) field



The electric and
the magnetic field
periodically are
built up and
destroyed.

$$f = \frac{1}{2\pi\sqrt{LC}}$$

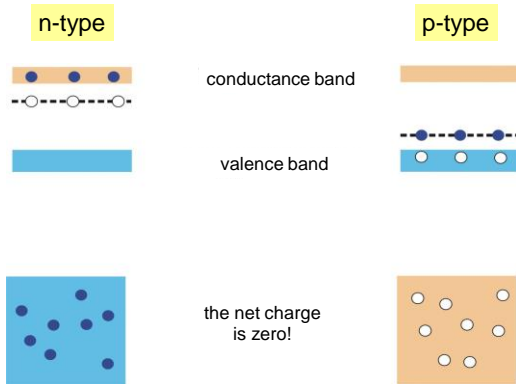
Resonance

Energy exchange between two oscillating systems is possible only if the resonant frequency of the two systems is enough close to each other.

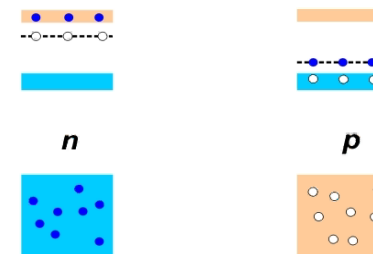
Tacoma bridge (1940)



Semiconductors



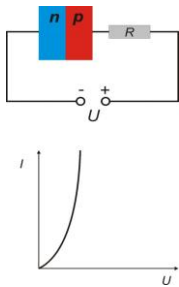
Diode



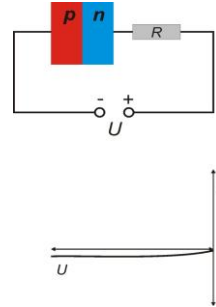
Consist of a n- and p-
type semiconductors
very close to each
other.

Working of a diode

forward direction

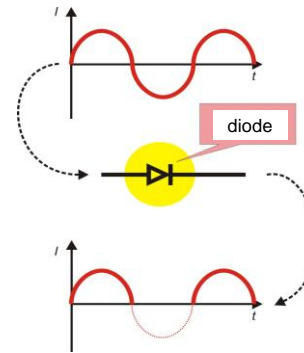


reversed direction

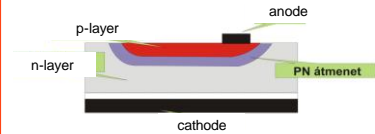


Application (examples)

rectification



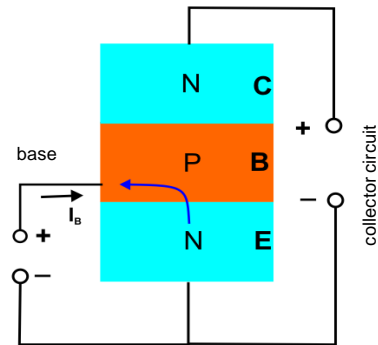
radiation detector



The radiation produces free charges and current in the case of reversed direction.

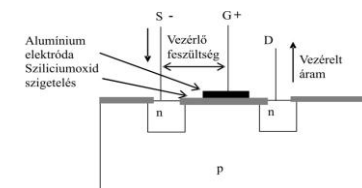
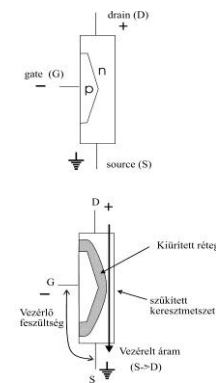
The transistor

It is built up from 3 layers.

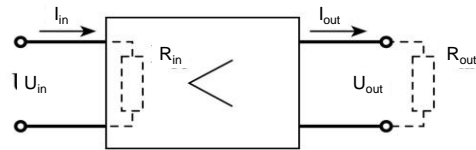


NPN transistor (there is PNP too)

FET and MOSFET



Amplifier



Power gain: (A_P)

Voltage gain: (A_U)

$$A_P = \frac{P_{out}}{P_{in}}$$

$$A_U = \frac{U_{out}}{U_{in}}$$

The decibel scale

Frequently instead of the simple proportion we use the logarithmic of them. Decibel-scale.

$$n = 10 \cdot \lg \frac{P_{out}}{P_{in}} \text{ (dB)}$$

$$P = \frac{U^2}{R}$$

$$A_P = \frac{U_{out}^2 / R_{out}}{U_{in}^2 / R_{in}} = \frac{U_{out}^2}{U_{in}^2} \cdot \frac{R_{in}}{R_{out}} = A_U^2 \cdot \frac{R_{in}}{R_{out}}$$

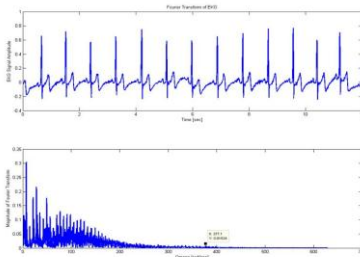
$$n(\text{dB}) = 10 \cdot \lg A_U^2 + 10 \cdot \lg \frac{R_{in}}{R_{out}} = 20 \cdot \lg A_U \left(+ 10 \cdot \lg \frac{R_{in}}{R_{out}} \right)$$



Fourier theoreme

$$y(t) = \sum_k a_k \sin(k \cdot \omega_0 \cdot t + \Phi_k)$$

Every periodic signal may be decomposed into the sum of sinusoidal signals.

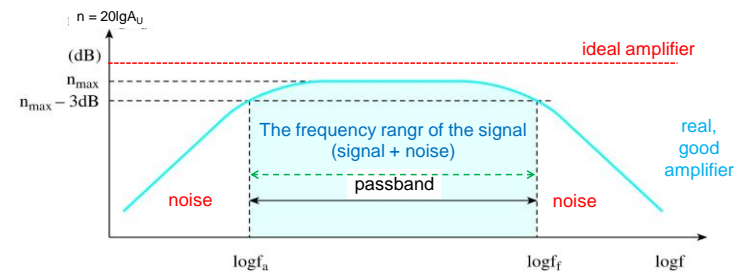


An ecg signal and it's frequency components.

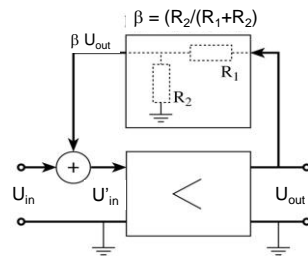
Transfer characteristics

The amplification in decibel as the function of the frequency.

In the presesnce of the noise the real amplifier is better.

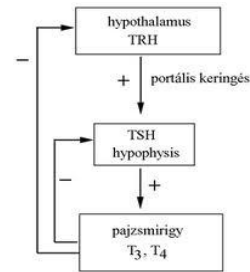


Feed-back



$$U'_{in} = U_{in} \pm \beta \cdot U_{out}$$

$$A_{U,F} = \frac{U_{out}}{U_{in}} = \frac{A_U}{1 \pm \beta \cdot A_U}$$

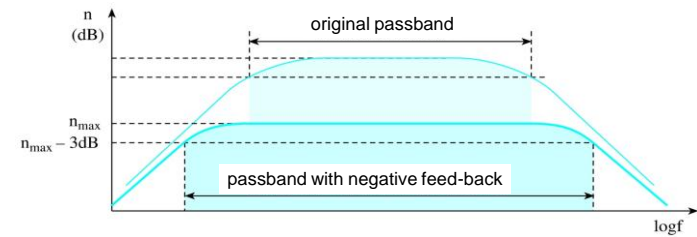


feed-back
in the body

Negative feed-back

The feed-backed part of the output is added to the input after inversion.

$$A_{U,NF} = \frac{U_{out}}{U_{in}} = \frac{A_U}{1 + \beta \cdot K_U}$$



Pozitive feed-back

The feed-backed part of the output is added to the input.

$$A_{U,PF} = \frac{U_{out}}{U_{in}} = \frac{A_U}{1 - \beta \cdot A_U}$$

if $\beta A_U = 1$ the system is unstable, oscillation.



Oscillators: used to produce electric signal.