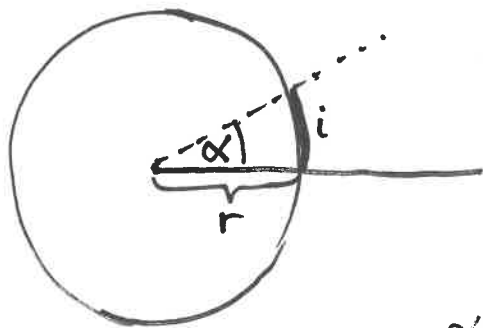


Angle

in RADIANS

$$\alpha = \frac{i}{r}$$

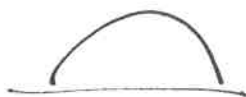


$[] \rightarrow$ unit / dimension of

$$[i] = m \quad [r] = m$$

$$[\alpha] = \frac{[i]}{[r]} = \frac{m}{m} = 1 \text{ rad}$$

$$\alpha = \frac{2\pi r}{r} = 2\pi \text{ rad} \quad \Leftrightarrow \begin{matrix} \text{degree } (^{\circ}) \\ 360^{\circ} \end{matrix}$$



π rad

180°

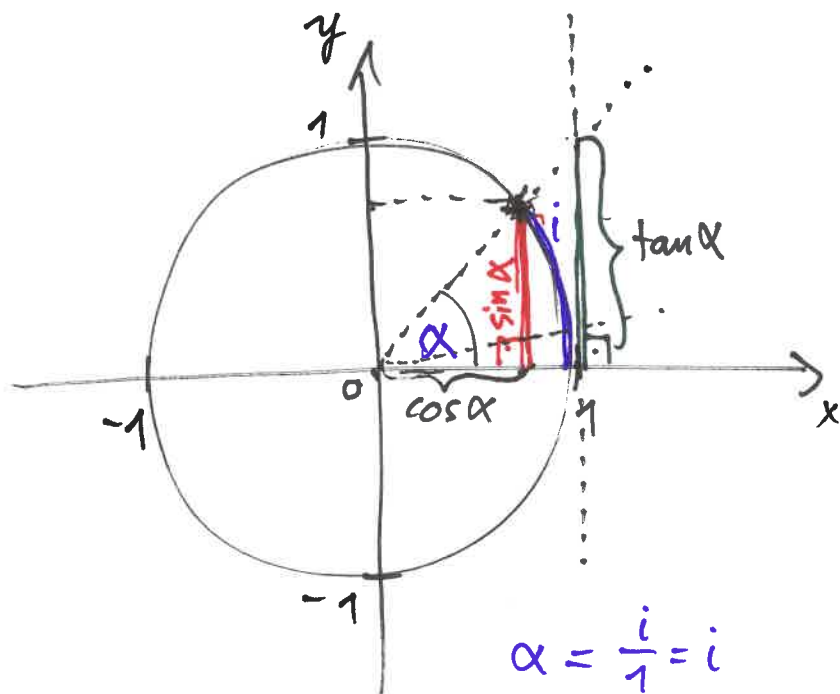
1 rad

β

proportional: equal ratios

$$\frac{1 \text{ rad}}{\pi \text{ rad}} = \frac{\beta}{180^{\circ}}$$

$$\beta = \frac{1}{\pi} \cdot 180^{\circ} = 57.3^{\circ}$$



$$\alpha = \frac{i}{1} = i$$

$$\sin \alpha =$$

N

for small angles
 $< 10^{\circ}$

$$\sin \alpha \lesssim \alpha \text{ (rad)} \lesssim \tan \alpha$$

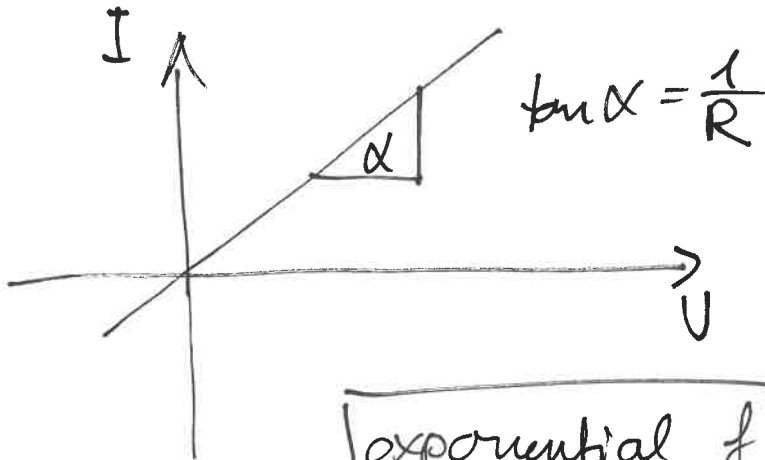
$$y = a \cdot x + b \quad \text{[linear fn]}$$

~~big~~
lin
exp
pow
log

$+1$ if $x=0$ then $y=b$ $+a$
 $+1$ if $x=1$ then $y=a+b$ $+a$
 $+1$ if $x=2$ then $y=2a+b$ $+a$

$$\Delta x = 1 \quad \Delta y = a$$

$$a = \frac{\Delta y}{\Delta x}$$



[exponential fn]

$$y = y_0 \cdot e^{-px}$$

$$\text{if } x=0 \text{ then } -px=0$$

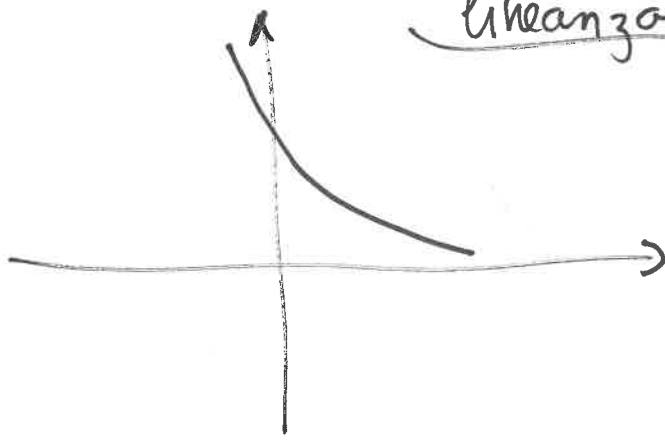
$$e^0 = 1$$

$$y = y_0 \cdot 1$$

$$\text{if } \frac{1}{p} = x \text{ then } -px = -1$$

$$e^{-1} = \frac{1}{e}$$

$$y = y_0 \cdot \frac{1}{e} = \frac{y_0}{e}$$



linearization

$$\log y = \log(y_0 \cdot e^{-p \cdot x}) \quad // \log$$

$$\log(y) = \log(y_0 \cdot e^{-p \cdot x})$$

$$\log(y) = \log(y_0) + \log(e^{-p \cdot x})$$

$$\log(y) = \log(y_0) + (-p \cdot x) \cdot \log(e)$$

$$\log(y) = -p \cdot \log(e) \cdot x + \log(y_0)$$

$$Y = a X + b$$

$$\log(a \cdot b) = \log(a) + \log(b)$$

$$\log(a^b) = b \cdot \log(a)$$