

Medical Biophysics II.

Biomechanics

Biomolecular and tissue mechanics

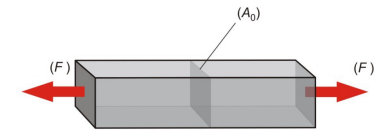
Zsolt Mártonfalvi

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Physical bases of biomechanics

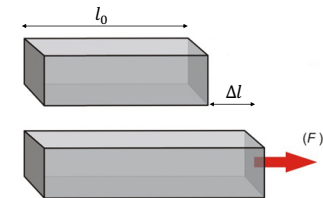
Stress

$$\sigma = \frac{F}{A_0} \quad \left[\frac{N}{m^2} = Pa \right]$$



Strain (deformation)

$$\varepsilon = \frac{\Delta l}{l_0} \quad \left[\frac{m}{m} \right] \text{ no dimension}$$



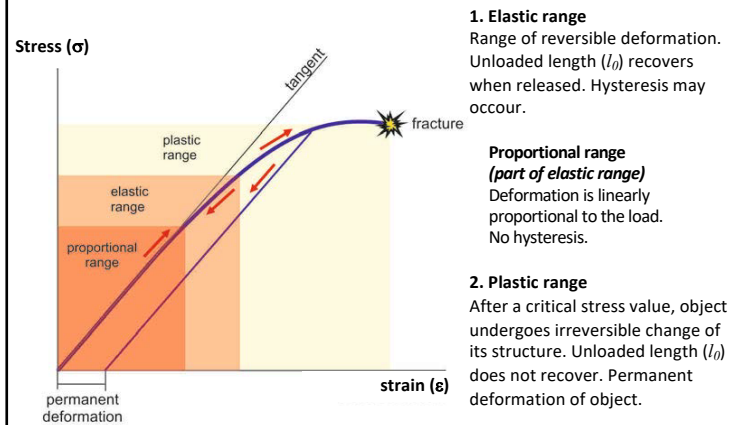
Strain is proportional to stress!

$$\sigma \sim \varepsilon$$

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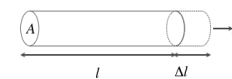
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Stress-strain diagram



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Hooke's law



$$\sigma = E \cdot \varepsilon$$

$$\frac{F}{A_0} = E \cdot \frac{\Delta l}{l_0} \quad \text{Hooke's law}$$

$$F = \frac{E \cdot A_0}{l_0} \cdot \Delta l$$

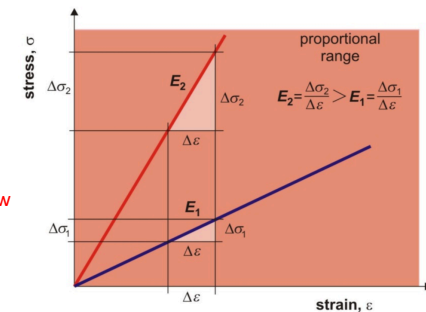
$$F = k \cdot \Delta l$$

Young's modulus
(material stiffness)

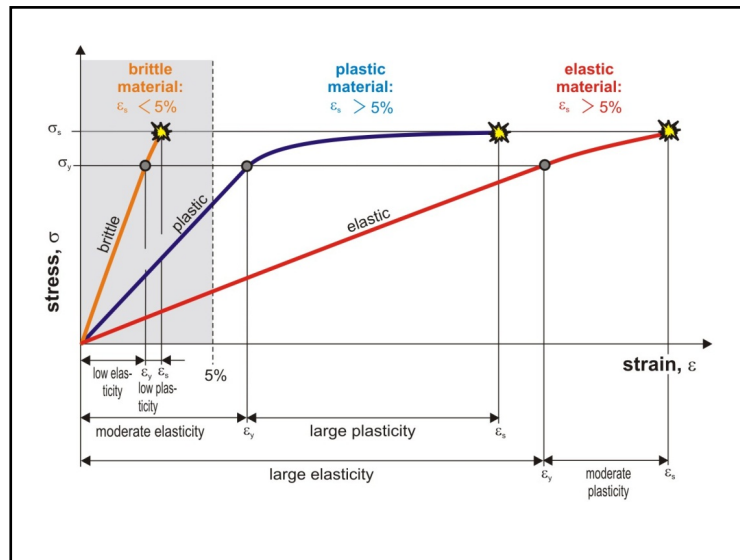
$$E = \frac{\sigma}{\varepsilon} = \frac{F}{A_0} \cdot \frac{l_0}{\Delta l} \quad E = \left[\frac{N}{m^2} = Pa \right]$$

Spring constant
(body stiffness)

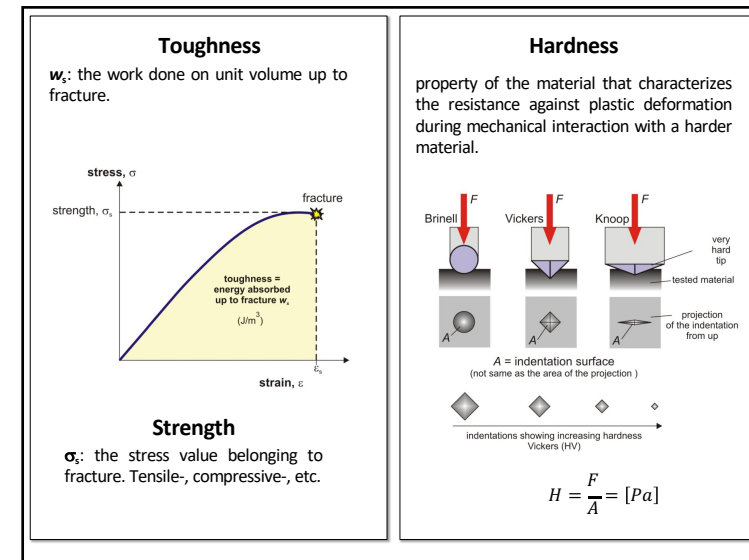
$$k = \frac{F}{\Delta l} \quad k = \left[\frac{N}{m} \right]$$



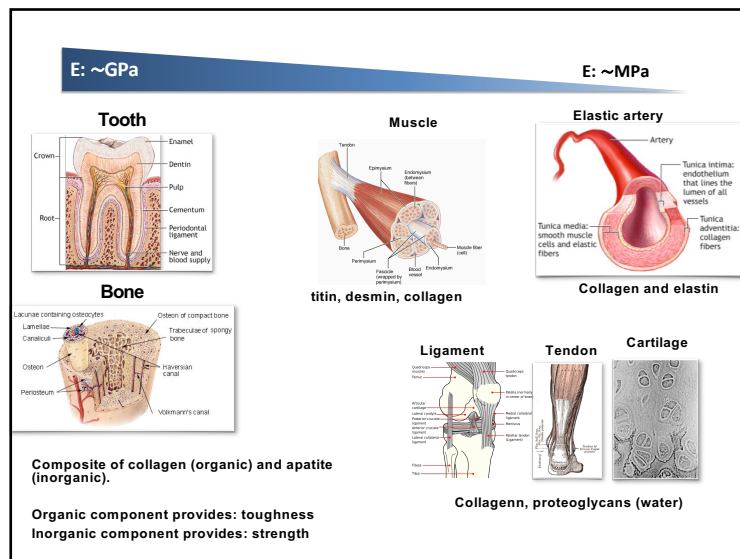
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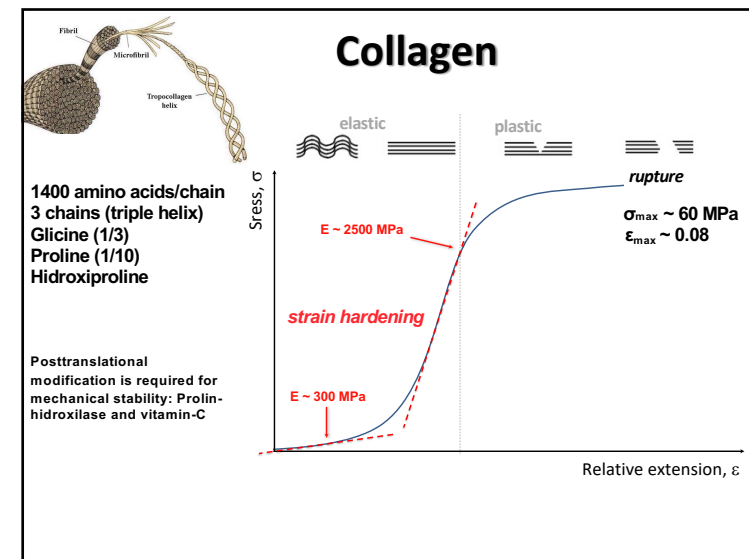
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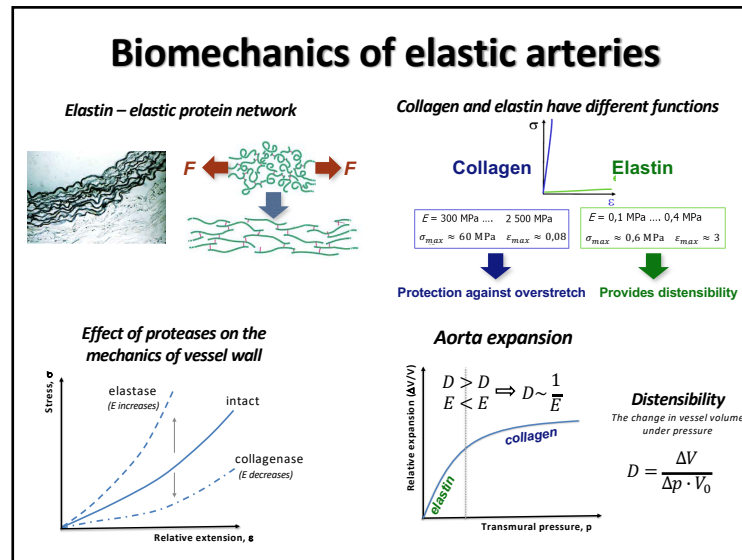
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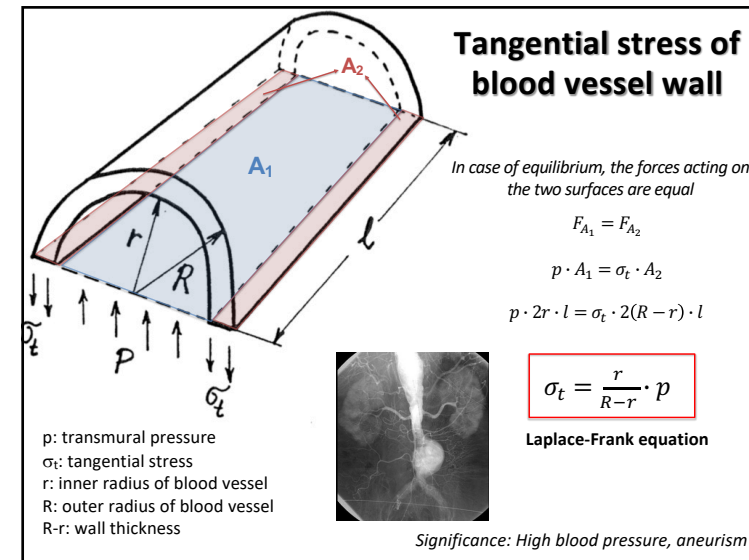
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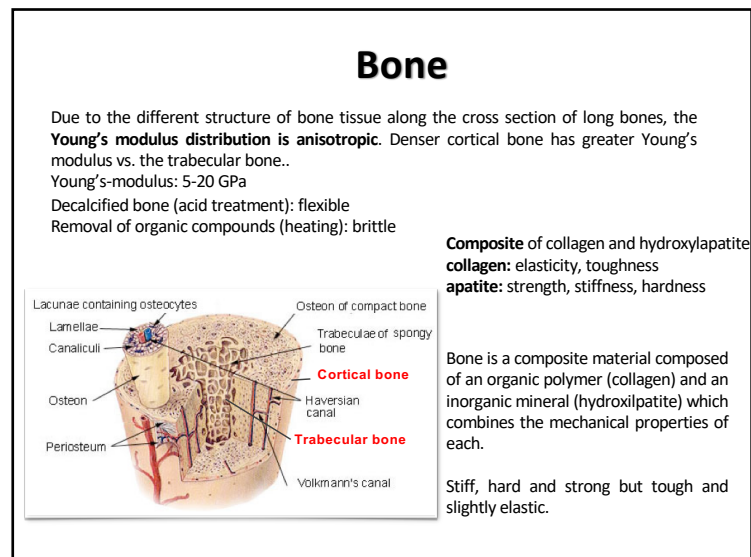
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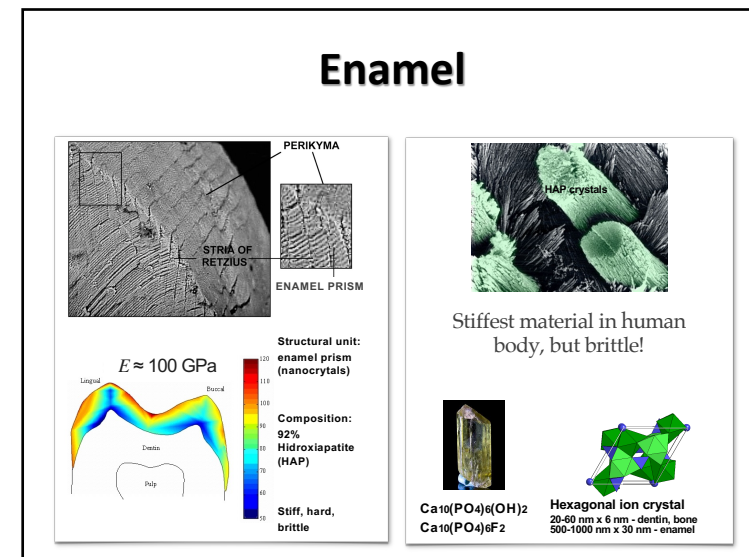
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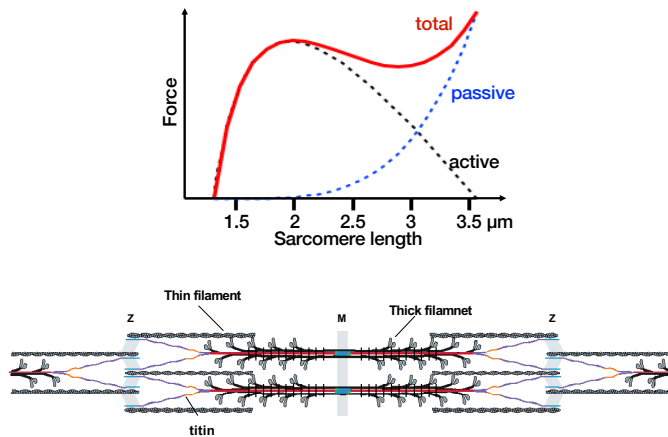


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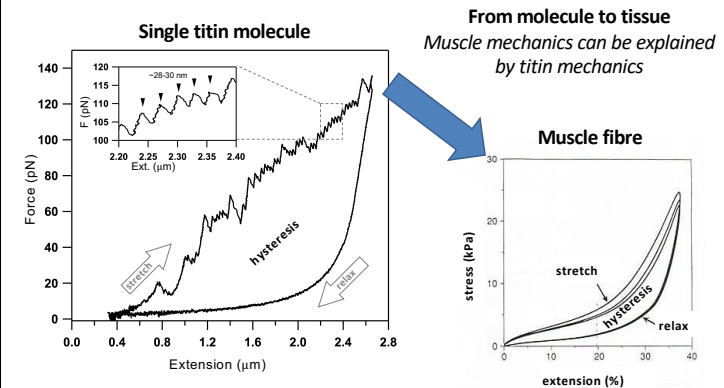
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Titin: the elastic filament of the sarcomere



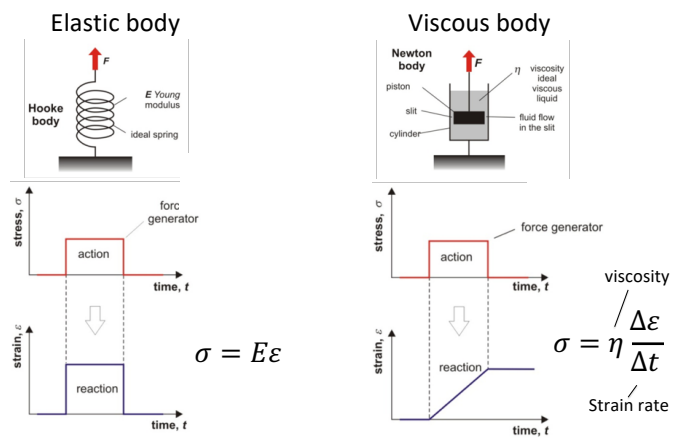
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Titin is the main determinant of muscle's passive elasticity



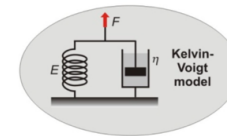
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Viscoelasticity (mechanical model)



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Viscoelasticity (mechanical model)



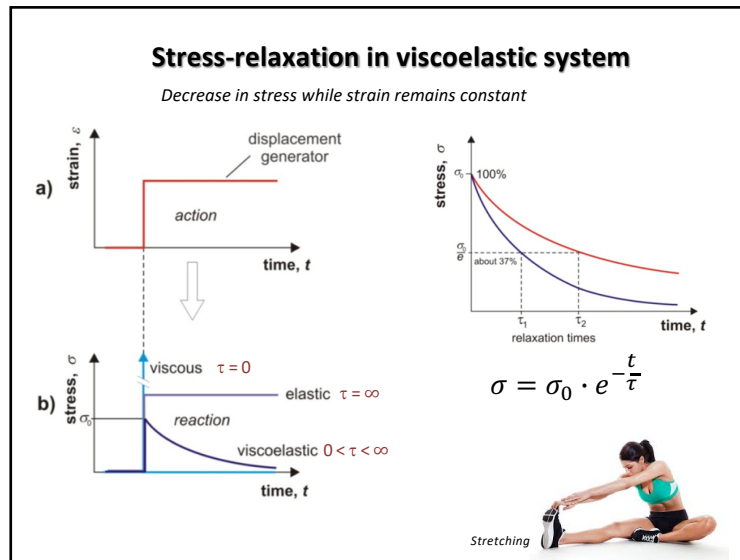
Viscoelasticity means the co-appearance of viscous and elastic behavior.

model: parallel connection of spring and dashpot (Kelvin-Voigt model)

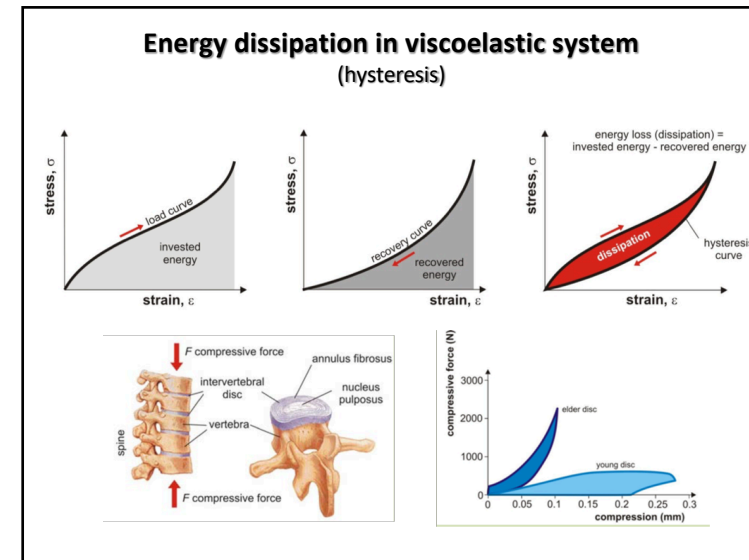
Spring: ideal elastic (Hooke) body
Dashpot: ideal viscous (Newton) body

1. Upon stretch, the extension of the spring is slowed down by the dashpot.
2. Extension stops when the elastic spring force equals the external force.
3. When the external force is quenched, the contraction of the spring is slowed down by the dashpot.

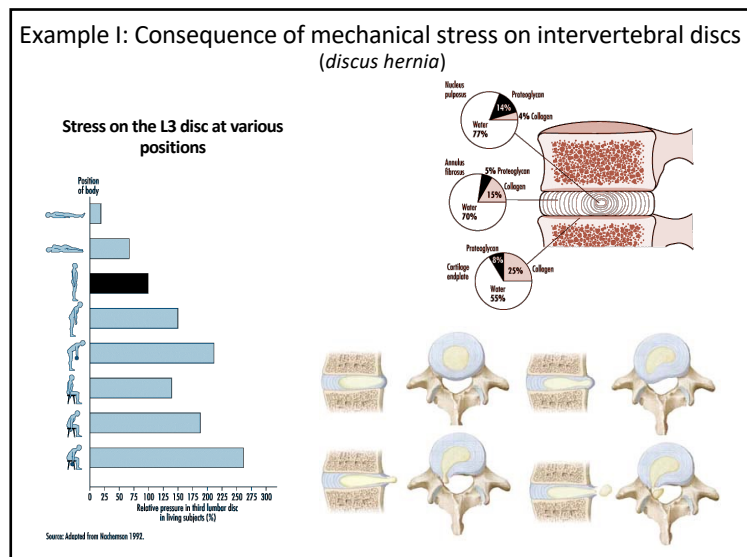
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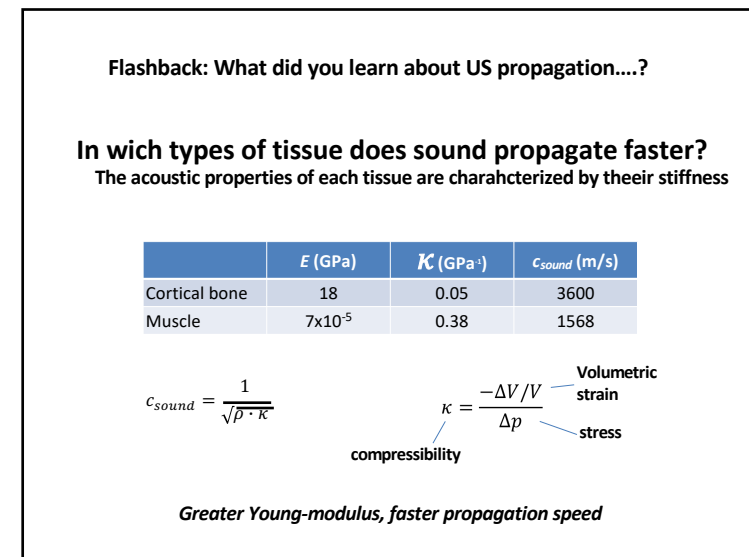
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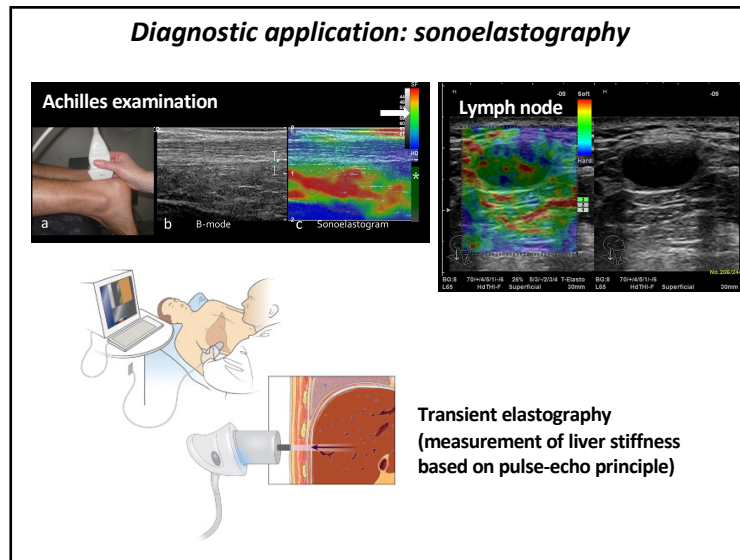
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